

Class 16: Discs and outflows: theory

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Outline

- Disc formation: the importance of magnetic fields
 - The magnetic braking problem
 - Possible solutions
- Theory of accretion discs
 - Viscous disc models
 - Sources of angular momentum transport
- Theory of outflows
 - Magnetocentrifugal launching
 - Angular momentum of the wind

Magnetic braking and disc formation

General considerations

- We showed that for collapse of a core of size $\sim \varpi_c$, conservation of specific angular momentum implies circularisation at $\varpi_d \sim \beta \varpi_c$
- However, magnetic fields are capable of transporting angular momentum via magnetic torques, so individual fluid elements may not conserve j
- Mechanism: as inner parts of core collapse, trying to conserve j , angular velocity has to go up, so inner parts of core rotate faster than outer parts
- This will twist magnetic field lines connecting inner and outer parts of core; the field will resist twisting, exerting a magnetic torque whose effect is to move j from faster rotating inner parts to slower rotating outer parts

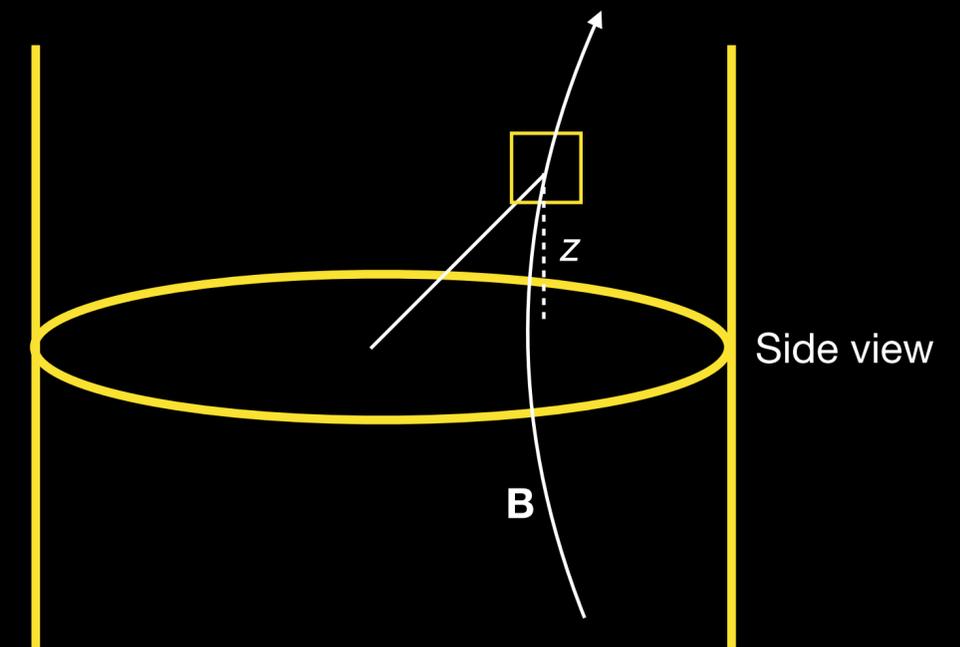
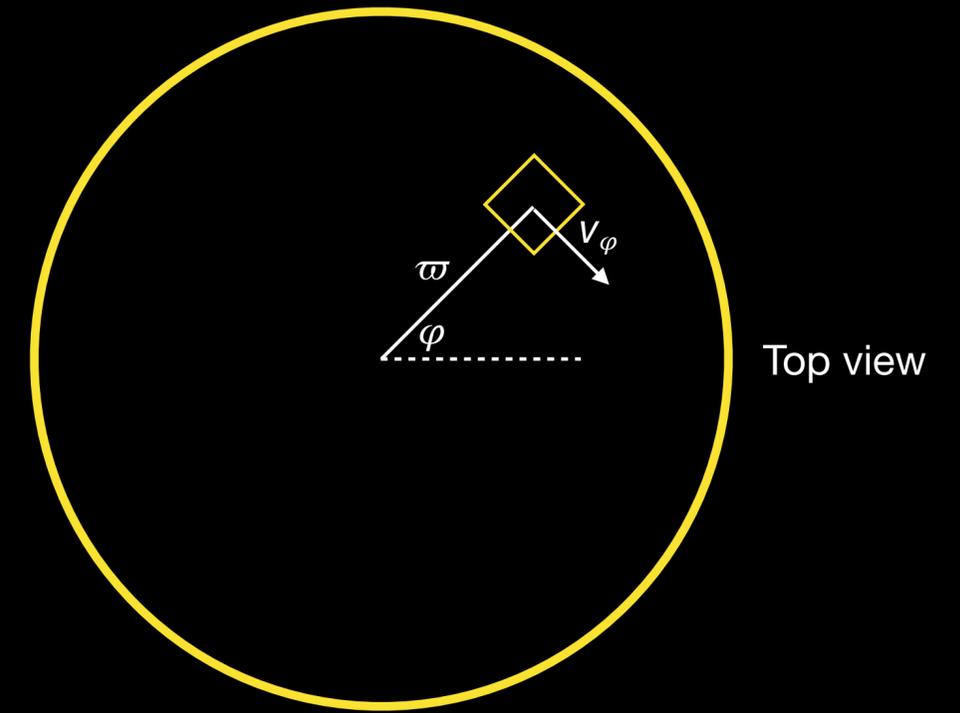
Estimate of braking effect

Part I

- Consider a fluid element at position (ϖ, φ, z) rotating at speed v_φ , threaded by magnetic field \mathbf{B}
- For convenience separate field into poloidal part $\mathbf{B}_p = (B_\varpi, B_z)$ and toroidal part B_φ
- Assuming axisymmetry, φ component of Lorentz force is

$$\begin{aligned}
 f_\varphi &= \frac{1}{4\pi} [(\nabla \times \mathbf{B}) \times \mathbf{B}] \cdot \hat{\phi} \\
 &= \frac{1}{4\pi} \left[\frac{B_\varpi}{\varpi} \frac{\partial}{\partial \varpi} (\varpi B_\phi) + B_z \frac{\partial B_\phi}{\partial z} \right] \\
 &= \frac{1}{4\pi \varpi} \mathbf{B}_p \cdot \nabla_p (\varpi B_\phi)
 \end{aligned}$$

ϖ and z parts of gradient



Estimate of braking effect

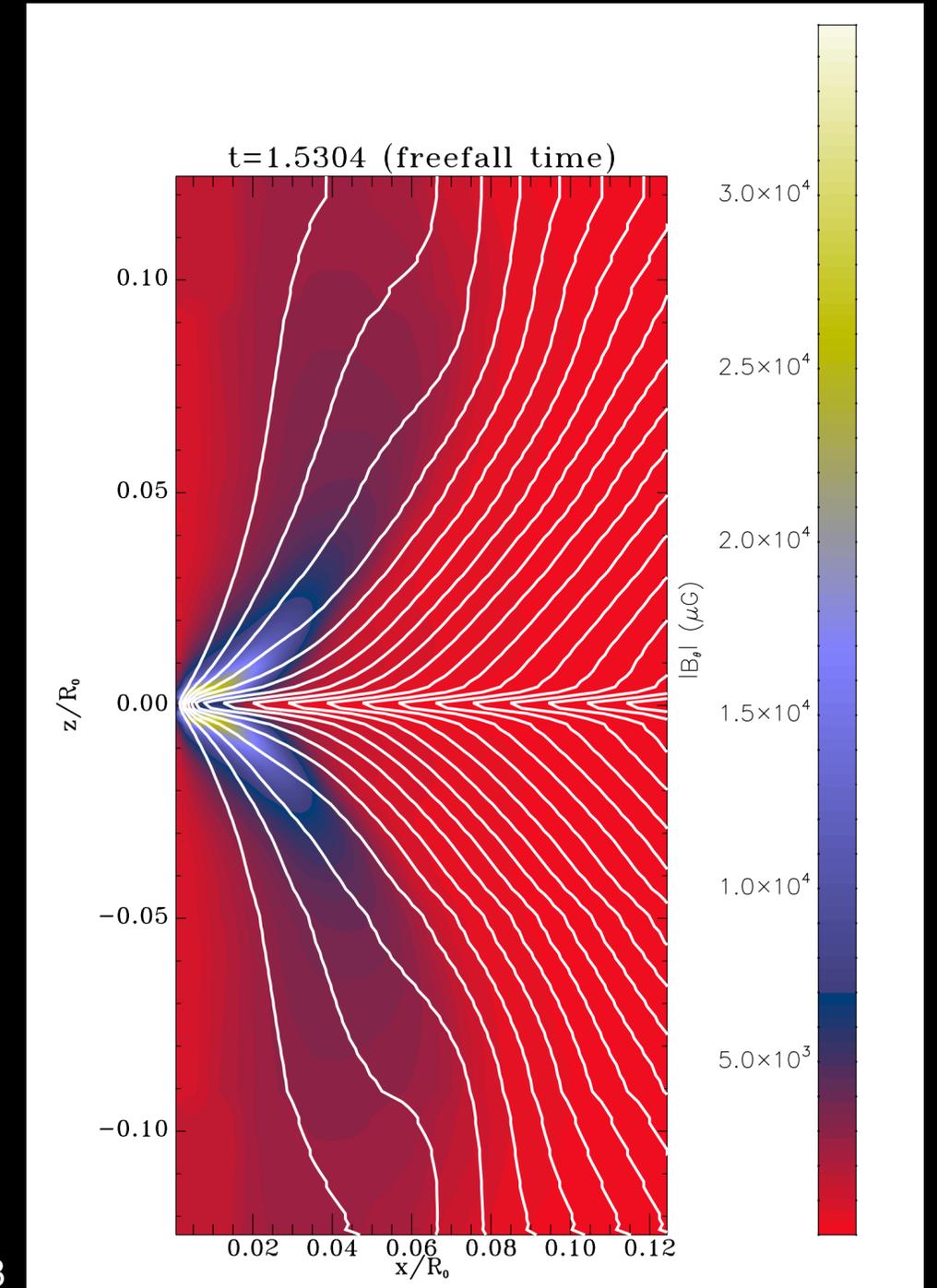
Part II

- In φ direction, $\frac{\partial}{\partial t}(\rho v_\phi) = f_\phi \implies \frac{\partial}{\partial t}(\rho v_\phi \varpi) = \frac{1}{4\pi} \mathbf{B}_p \cdot \nabla_p (\varpi B_\phi)$
- Define braking time $t_{\text{br}} = \frac{\rho v_\phi \varpi}{\frac{\partial}{\partial t}(\rho v_\phi \varpi)} = \frac{4\pi \rho v_\phi \varpi}{\mathbf{B}_p \cdot \nabla_p (\varpi B_\phi)}$
- Consider fluid element trying circularise at speed $v_\phi = (GM/\varpi)^{1/2}$, where $M \sim (4\pi/3)\rho\varpi^3$ is mass already collapsed; braking time is $t_{\text{br}} \sim \frac{(4\pi\rho)^{3/2} G^{1/2} \varpi^2}{\mathbf{B}_p \cdot \nabla_p (\varpi B_\phi)}$
- Assuming \mathbf{B} varies on scale ϖ , so $\mathbf{B}_p \cdot \nabla_p (\varpi B_\phi) \sim B^2$, then
$$t_{\text{br}} \sim \frac{G^{1/2} \rho^{3/2} \varpi^2}{B^2} \sim \frac{(G\rho)^{1/2} \varpi^2}{v_A^2} \sim \frac{t_{\text{cr}}^2}{t_{\text{ff}}}$$
- Bottom line: if $\mathcal{M}_A \sim 1$, so $t_{\text{cr}} \sim t_{\text{ff}}$, then $t_{\text{br}} \sim t_{\text{ff}} \rightarrow$ magnetic braking significant

The magnetic braking problem

Simulation results

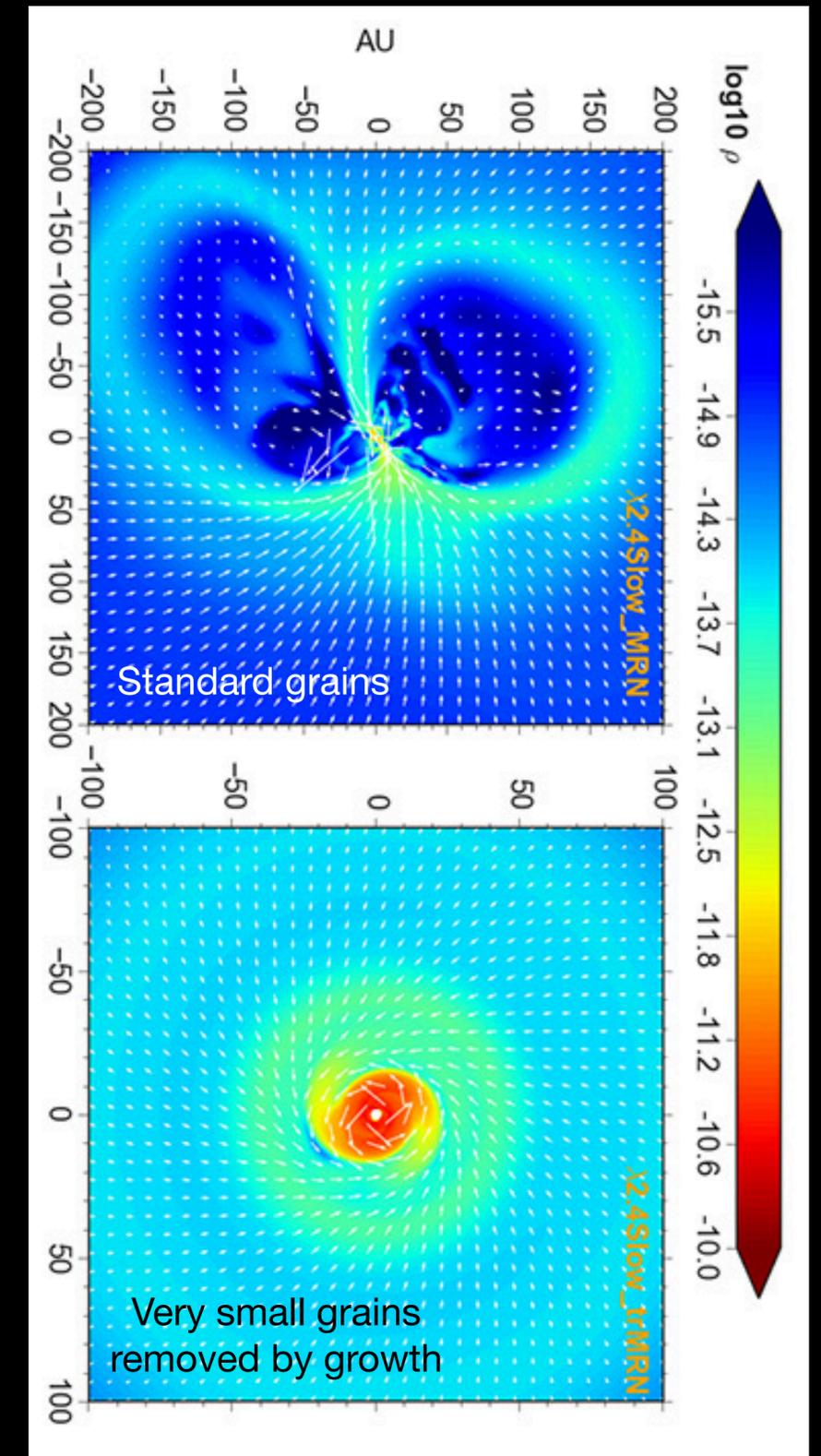
- Simulations with ideal MHD show that magnetic braking is strong enough to prevent Keplerian discs from forming entirely
- Instead, pseudo-discs supported by magnetic field forms
- Problem: we observe Keplerian discs
- So how do we get around this?



Avoiding magnetic braking

Possible solutions

- Ambipolar diffusion and Hall effect may allow enough B field to escape gas to let discs form
 - Depends crucially on microphysics: at high density, charge mostly carried by dust grains
 - Conductivity depends strongly on number of very small ($\sim 1-10$ nm) grains; if these are removed by growth, much less magnetic braking
- Magnetic braking much less effective when flow is turbulent, due to misalignment between magnetic torques and angular momentum



Evolution of discs

Mass conservation

- Consider a geometrically-thin, axisymmetric disc of surface density Σ orbiting with angular velocity Ω

- Vertically-integrated equation of mass conservation:

$$\frac{\partial \rho}{\partial t} + \nabla \cdot (\rho \mathbf{v}) = \frac{\partial \rho}{\partial t} + \frac{1}{\varpi} (\varpi \rho v_{\varpi}) = 0 \quad \implies \quad \frac{\partial \Sigma}{\partial t} + \frac{1}{\varpi} \frac{\partial}{\partial \varpi} (\varpi \Sigma v_{\varpi}) = 0$$

- Define inward mass flux $\dot{M} = -2\pi\varpi\Sigma v_{\varpi}$

- Equation of mass conservation: $\frac{\partial \Sigma}{\partial t} - \frac{1}{2\pi\varpi} \frac{\partial \dot{M}}{\partial \varpi} = 0$

Evolution of discs

Angular momentum conservation

- Start with Navier-Stokes equation: $\rho \left(\frac{\partial \mathbf{v}}{\partial t} + \mathbf{v} \cdot \nabla \mathbf{v} \right) = -\nabla p - \rho \nabla \psi + \nabla \cdot \mathbf{T}$

Gravitational potential $\nabla \psi$ Viscous stress tensor \mathbf{T}
- Vertically integrate: $\Sigma \left(\frac{\partial \mathbf{v}}{\partial t} + \mathbf{v} \cdot \nabla \mathbf{v} \right) = -\nabla P - \Sigma \nabla \psi + \int \nabla \cdot \mathbf{T} dz$

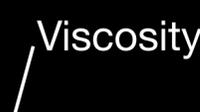
Vertically-integrated pressure P
- Write out ϕ component, using axisymmetry to drop all ϕ derivatives:

$$\Sigma \left[\frac{\partial v_\phi}{\partial t} + \frac{v_\varpi}{\varpi} \frac{\partial}{\partial \varpi} (\varpi v_\phi) \right] = \int \frac{1}{\varpi^2} \frac{\partial}{\partial \varpi} (\varpi^2 T_{\varpi\phi}) dz$$
- Multiply by $2\pi\varpi^2$: $2\pi\varpi\Sigma \left(\frac{\partial j}{\partial t} + v_\varpi \frac{\partial j}{\partial \varpi} \right) = \int \frac{\partial}{\partial \varpi} (2\pi\varpi^2 T_{\varpi\phi}) dz \equiv \frac{\partial \mathcal{T}}{\partial \varpi}$

$T_{\varpi\phi} = \text{Force / area}$
 $\varpi T_{\varpi\phi} = \text{Torque / area}$
- Here $j = \varpi v_\phi$ is the specific angular momentum, and $\mathcal{T} = 2\pi\varpi \int \varpi T_{\varpi\phi} dz$ is the viscous torque exerted by one ring of fluid on its neighbour

Steady viscous discs

Torque and viscosity

- If gas is in Keplerian orbit at all times, then $j = \sqrt{GM_*\varpi}$ $\frac{\partial j}{\partial \varpi} = \frac{1}{2}\sqrt{\frac{GM_*}{\varpi}}$ $\frac{\partial j}{\partial t} = 0$
- Plug into equations: $\dot{M} = -\left(\frac{\partial j}{\partial \varpi}\right)^{-1} \frac{\partial \mathcal{T}}{\partial \varpi}$ → viscous torque sets accretion rate
- Stress $T_{\varpi\phi}$ scales with rate of strain, defined as inverse of timescale required for adjacent fluid elements shear apart by a distance of order their separation
- For gas parcels at radii separated by $d\varpi$, relative velocity $dv_\phi = \varpi d\Omega$, so rate of strain = $dv_\phi/d\varpi = \varpi (d\Omega/d\varpi)$
- Thus can write $T_{\varpi\phi} = \rho\nu\varpi \frac{d\Omega}{d\varpi} \implies \mathcal{T} = 2\pi\varpi^3 \Sigma \nu \frac{d\Omega}{d\varpi}$


Steady viscous discs

Evolution equation and solutions

- Plugging in torque gives $\frac{\partial \Sigma}{\partial t} = \frac{3}{\varpi} \frac{\partial}{\partial \varpi} \left[\varpi^{1/2} \frac{\partial}{\partial \varpi} \left(\nu \Sigma \varpi^{1/2} \right) \right]$ $v_{\varpi} = -\frac{3}{\Sigma \varpi^{1/2}} \frac{\partial}{\partial \varpi} \left(\nu \Sigma \varpi^{1/2} \right)$

- Can solve numerically, but illuminating to consider trivial case Σ, ν constant:

$$v_{\varpi} = -\frac{3}{2} \frac{\nu}{\varpi} \quad \dot{M} = 3\pi \Sigma \nu$$

- Thus ν sets accretion rate — but what is ν ? Since torque has units of pressure, it is common to non-dimensionalise by scaling the pressure:

Shakura-Sunyaev α parameter \rightarrow

$$T_{\varpi\phi} = -\alpha p \frac{\Omega/\varpi}{d\Omega/d\varpi} \iff \nu = \alpha \frac{c_s^2}{\Omega} \iff \dot{M} = 3\pi \alpha \Sigma \frac{c_s^2}{\Omega}$$

- Note: accretion timescale $t_{\text{acc}} \sim \frac{M_{\text{disc}}}{\dot{M}} \sim \alpha \frac{M}{\Sigma} \frac{\Omega}{c_s^2} \sim \alpha \frac{\Omega}{(c_s/R_{\text{disc}})^2} \sim \alpha \left(\frac{t_{\text{orb}}}{t_{\text{cross}}} \right)^2 t_{\text{orb}}$

- Thus value of α sets ratio of accretion time to orbital time

Angular momentum transport mechanisms

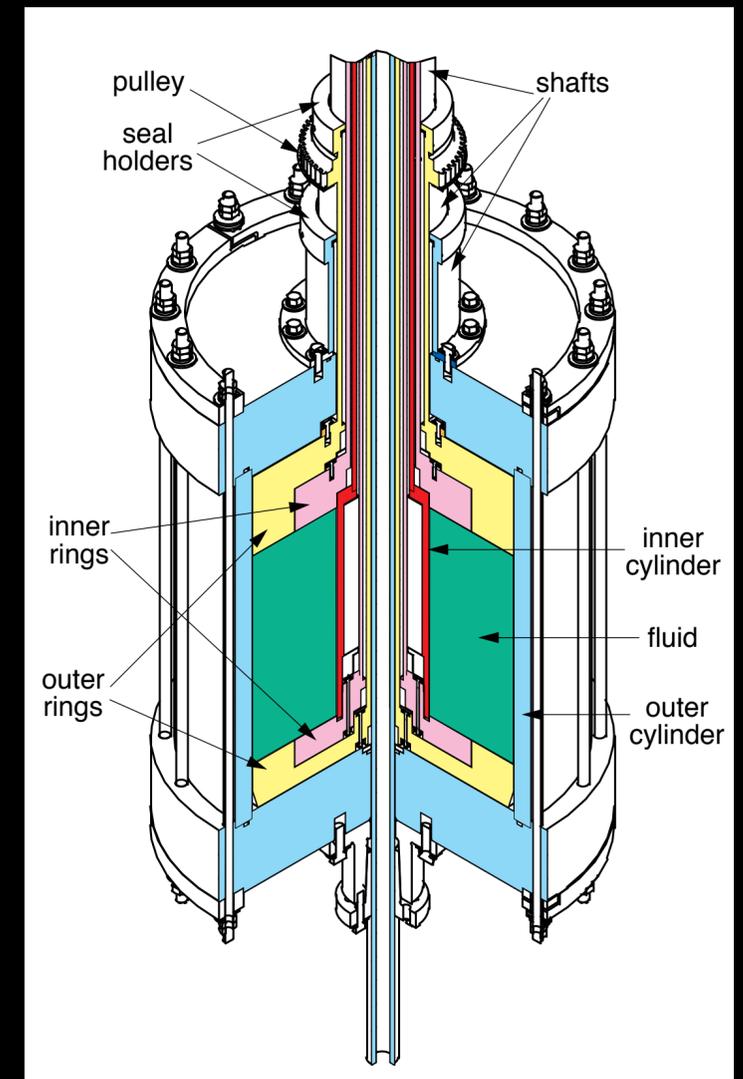
What is responsible for setting α ?

- Empirically measured accretion rates on young stars suggest $\alpha \sim 0.01$, but mechanism by which this is established still debated
- Cannot be ordinary fluid viscosity: $\alpha = \frac{\Omega}{c_s^2} \nu \sim \frac{\Omega}{c_s^2} \left(\frac{c_s}{n\sigma} \right)$
Sound speed
Number density \times cross section
- Plugging in $\Omega \sim 1/\text{yr}$, $c_s \sim 1 \text{ km/s}$, $n \sim 10^{12} \text{ cm}^{-3}$, $\sigma \sim (1 \text{ nm})^2$ gives $\alpha \sim 10^{-10}$.
Accretion time would be longer than Hubble time!
- Other possibilities: (1) hydrodynamic turbulence, (2) MHD turbulence, (3) gravitational torques, (4) winds

Hydrodynamic turbulence

Doesn't work

- Viscosity is a diffusion-like term: measures mean distance something (momentum or angular momentum) travels, multiplied by speed with which it travels
- Molecular viscosity negligible because particle mean free path is small, but turbulence can create coherent motions on scales up to \sim disc scale height — could in principle transport angular momentum faster
- However, both simulations and laboratory experiments show little j transport by hydrodynamic turbulence: $\alpha \approx 10^{-6}$



MHD turbulence

Magnetorotational instability (MRI)

- Basic mechanism: fluid elements tethered by magnetic field line, one closer to star
- Element closer to star tries to rotate faster, move ahead of slower, more distant one
- Field resists being sheared apart, pulls back on inner element, forward on outer element — transfers j
- This makes inner element slow down, so it falls even further inward; outer element goes outward: force gets even bigger → instability

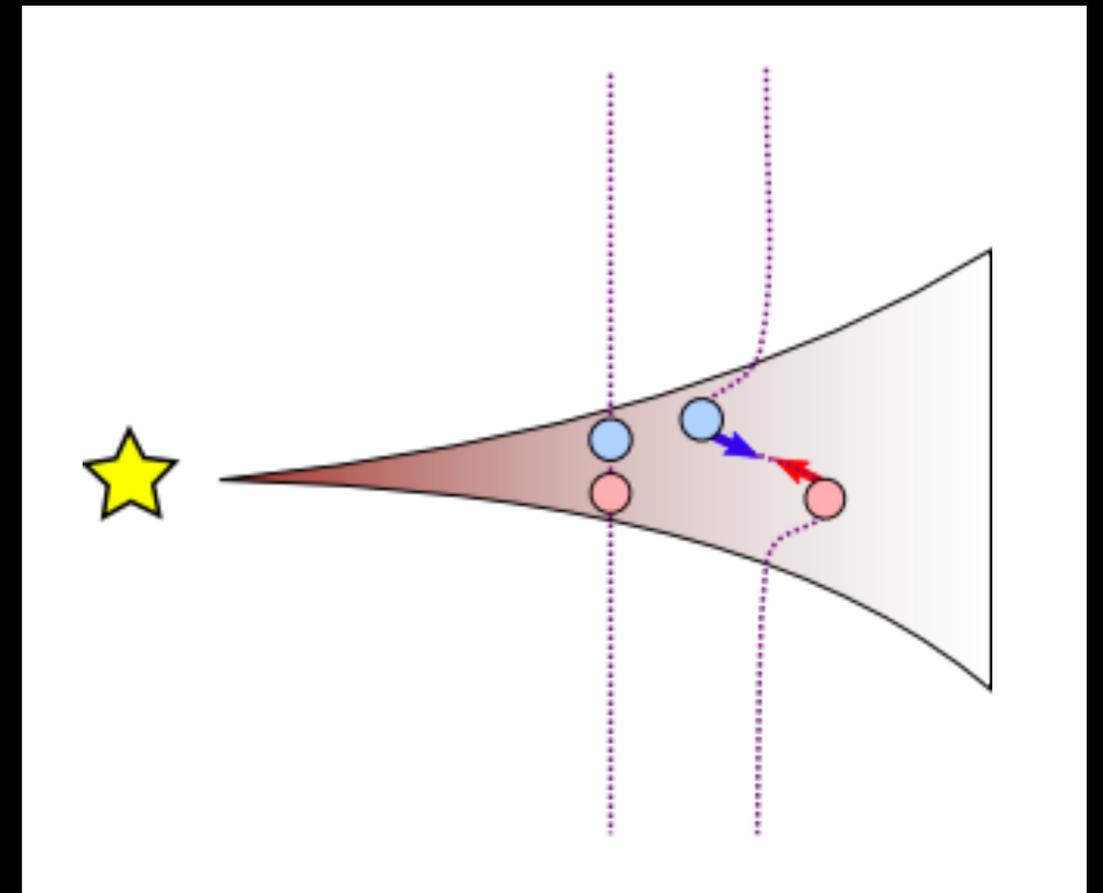


Diagram from Harvard Ay201b “book”

MRI advantages and disadvantages

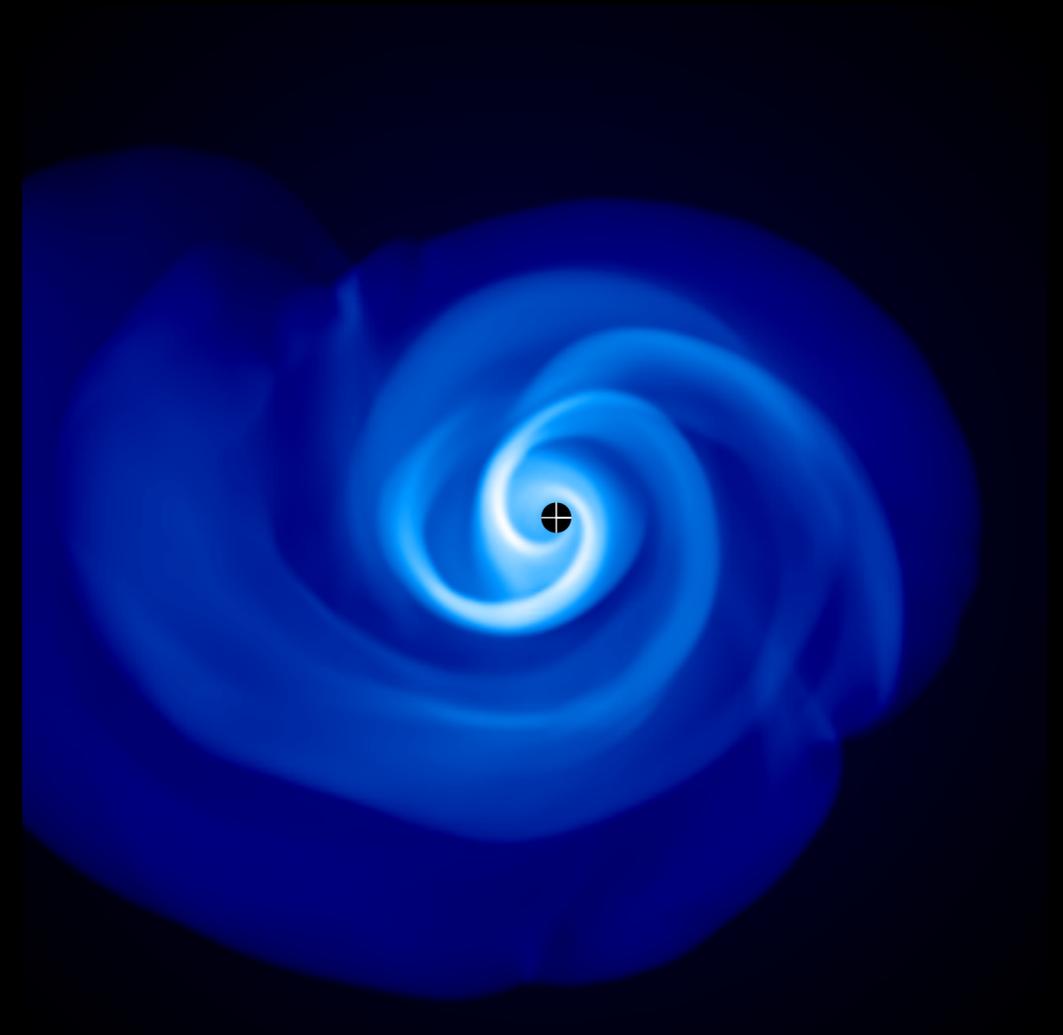
Still undecided if this is the right model

- Simulations show MRI provides about the right value of α
- Big uncertainty is coupling of field to gas: high density in discs, so ion fraction likely to be very, very low — B field may not be coupled enough to gas to allow MRI to take place
- May also depend on height within disc: surface layers exposed to stellar radiation could be ionised and MRI-active, while mid plane has lower ionisation and be an MRI “dead zone”

Gravity-driven accretion

Discs near $Q = 1$

- For discs massive enough to be self-gravitating, instabilities produce spiral arms
- These efficiently transport angular momentum (more in paper by Kratter+)
- May be dominant accretion process during main accretion phase of star, when accretion rate is high and disc is massive
- However, accretion also observed in class II systems where disc is at $Q \gg 1$; that can't be GI

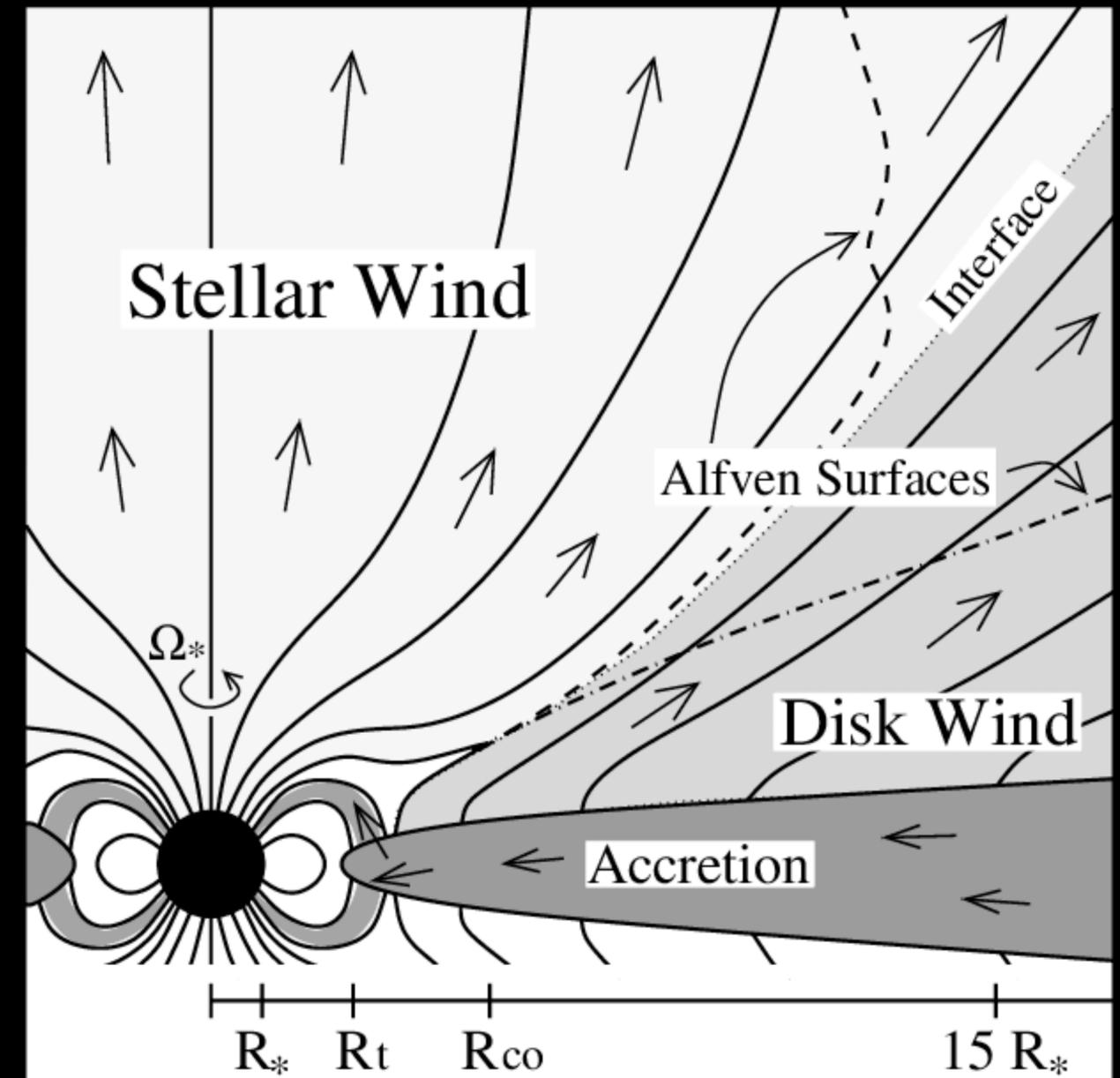


Kratter+ 2010

Discs winds and wind-driven accretion

Basic considerations

- Magnetised accretion discs generically drive winds
- Power source distinct from stellar winds, which are given by thermal or radiation pressure, and ultimately power by star
- Disc winds are powered by energy released by accretion
- This potentially makes them much more powerful than ordinary stellar winds



Matt & Pudritz (2005)

Theory of disc winds

The basics

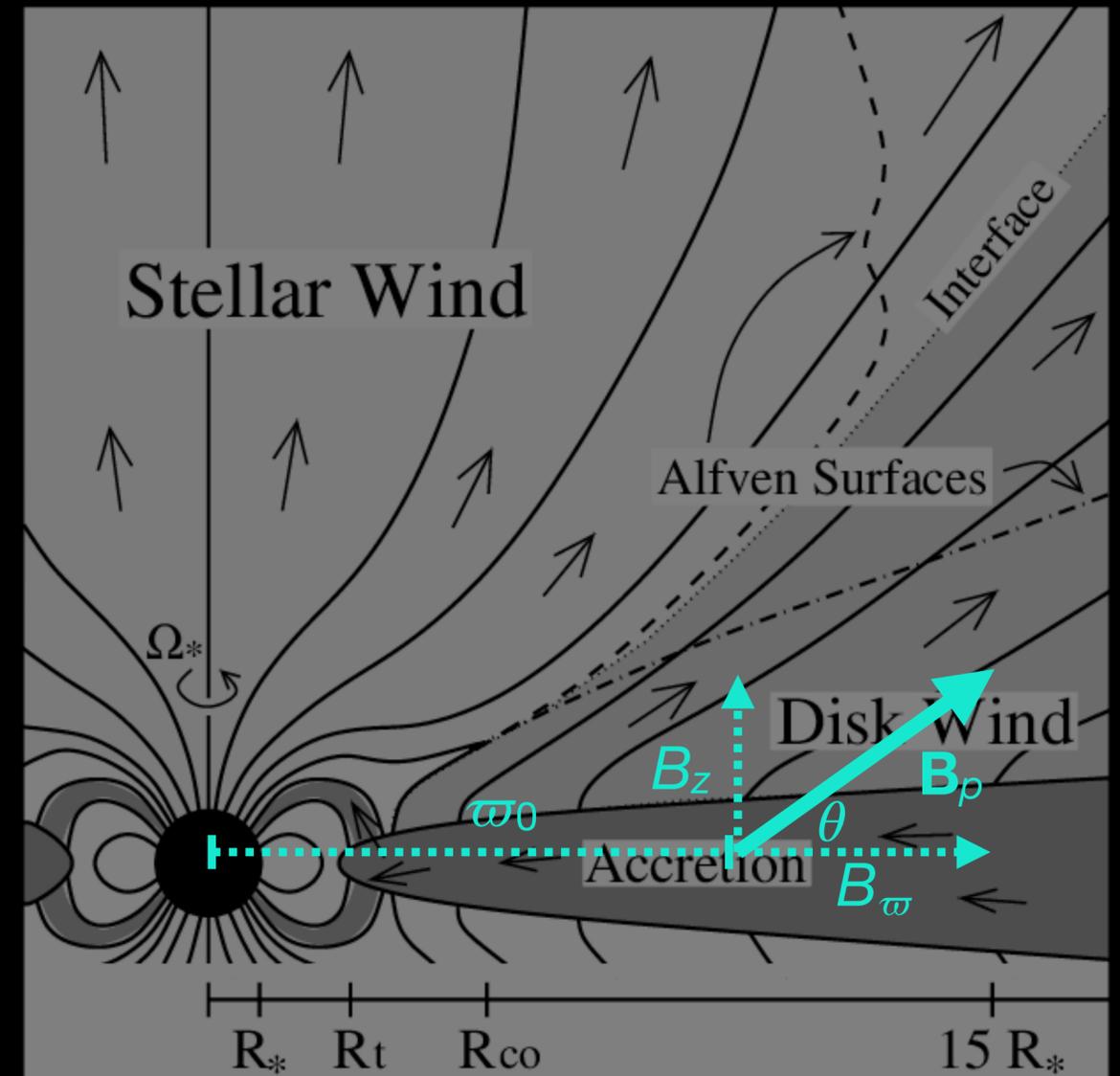
- Write magnetic field as sum of toroidal and poloidal parts: $\mathbf{B} = \mathbf{B}_p + B_\phi \hat{\phi}$
- Consider region slightly above disc plane; in this region magnetic pressure \gg gas pressure, so approximate field in this region as rigidly rotating at speed Ω
- Gas subject to two potentials (in rotating frame): $\psi = \psi_g + \psi_c = -\frac{GM_*}{\sqrt{\varpi^2 + z^2}} - \frac{1}{2}\Omega^2\varpi^2$
Gravitational potential Centrifugal potential
- Assume gas is fixed to field line that is anchored to disc in mid plane at distance ϖ_0 , so $\Omega = (GM_* / \varpi_0^3)^{1/2}$; then potential is

$$\psi = -\frac{GM_*}{\varpi_0} \left[\frac{1}{2} \left(\frac{\varpi}{\varpi_0} \right)^2 + \frac{\varpi_0}{\sqrt{\varpi^2 + z^2}} \right]$$

Force and stability analysis

- Force due to potential: $\mathbf{f} = -\nabla\psi = -GM_* \left\{ \varpi \left[\frac{1}{(\varpi^2 + z^2)^{3/2}} - \frac{1}{\varpi_0^3} \right] \hat{\varpi} + \frac{z}{(\varpi^2 + z^2)^{3/2}} \hat{z} \right\}$
- Define $\cos\theta = B_\varpi / \sqrt{B_\varpi^2 + B_z^2}$
- Consider fluid parcel at mid plane displaced along field by ds , to $(\varpi, z) = (\varpi_0 + \cos\theta ds, \sin\theta ds)$
- It feels force $d\mathbf{f} = \frac{GM_*}{\varpi_0^3} (3 \cos\theta \hat{\varpi} - \sin\theta \hat{z}) ds$
- Component parallel to field is:

$$df_{\parallel} = \frac{GM_*}{\varpi_0^3} (3 \cos^2\theta - \sin^2\theta) ds$$
- Implication: if $\theta < 60^\circ$, $df_{\parallel} > 0$: parcel flows out as part of a wind



Wind angular momentum and accretion

- Outflowing material held in solid-body rotation by field, so $v = \varpi\Omega$
- Clearly this must break down for sufficiently large ϖ — otherwise we would eventually have $v > c$
- Breakdown occurs when wind velocity \sim Alfvén speed, because at this point field is not “rigid” enough to keep forcing material to rotate as solid body — radius at which this occurs is called Alfvén radius ϖ_A
- Specific angular momentum of wind material is therefore $j = \varpi_A v = \varpi_A^2 \Omega$, larger than that of disc material by $(\varpi_A/\varpi_0)^2$
- Thus wind can remove all j and allow accretion if $\dot{M}_w \geq \left(\frac{\varpi_0}{\varpi_A}\right)^2 \dot{M}_*$