

# Magnetohydrodynamics (MHD)

- First we assume that the fluid is almost completely neutral, with only a small charge density  $\rho_e$  present. This condition can be written

$$\rho_e v \sim \frac{v^2}{c^2} j, \quad (1)$$

where  $\rho_e$  is small. (Will check Eq. (1) at the end.)

Here,  $\vec{v}$  is the gas velocity, and  $j$  is the current density, which has units of current per unit area.

- Assumption Eq. (1) is reasonable, because for a good conductor, any net charge would immediately be neutralised by a current. An important consequence of this assumption is that in MHD there are practically no electric fields, i.e., any charge separation would lead to currents that immediately destroy the  $\vec{E}$  field. However, the currents produce a magnetic field  $\vec{B}$ ; hence the name "Magnetohydrodynamics".

- Now we need to couple Maxwell's equations (in the non-relativistic approximation, i.e.,  $v/c \approx 0$ ) with the momentum eq. of hydrodynamics.

- Maxwell's equations (in CGS units):

$$\begin{aligned}\nabla \cdot \vec{E} &= 4\pi \rho_e & (2) \\ \nabla \cdot \vec{B} &= 0 & (3) \\ \nabla \times \vec{E} &= -\frac{1}{c} \partial_t \vec{B} & (4) \\ \nabla \times \vec{B} &= \frac{4\pi}{c} \vec{j} + \frac{1}{c} \partial_t \vec{E} & (5)\end{aligned}$$

- In a highly conducting fluid, we expect the fields to vary on the same length  $L$  and time scale  $T$  as the fluid itself, where  $L/T \sim v$  is the fluid velocity, i.e., the  $\vec{B}$  field is basically produced/maintained by the fluid motion.
- Approximating  $\nabla \rightarrow L^{-1}$  and  $\partial_t \rightarrow T^{-1}$ , the 3rd Maxwell eq.,  $\nabla \times \vec{E} = -\frac{1}{c} \partial_t \vec{B}$ , says that the  $\vec{E}$  field is a factor  $v/c$  smaller than the  $\vec{B}$  field:

$$E \sim \frac{v}{c} B \quad (6)$$

- Using this, we see that the "displacement current" in the last Maxwell eq. (the term  $\frac{1}{c} \partial_t \vec{E}$ ) can be neglected, because it is of order  $v^2/c^2$ :

$$\Rightarrow \nabla \times \vec{B} = \frac{4\pi}{c} \vec{j} \quad (7)$$

- Now we need to couple this to the fluid equations.  
First, the EM force is the Lorentz force (per unit volume) :

$$\vec{F}_L = \rho_e \vec{E} + \frac{1}{c} \vec{j} \times \vec{B} \quad (8)$$

- Thanks to our assumption, Eq. (1), and using Eq. (6), we see the  $\vec{E}$  field term in Eq. (8) is small and can be neglected, hence

$$\vec{F}_L = \frac{1}{c} \vec{j} \times \vec{B} \quad (9)$$

- Thus, the Euler eq. with the addition of the Lorentz force becomes

$$\rho \frac{D\vec{v}}{Dt} = -\nabla P + \frac{1}{c} \vec{j} \times \vec{B} \quad (10)$$

- Using Eq. (7),  $\nabla \times \vec{B} = \frac{4\pi}{c} \vec{j}$ , this becomes

$$\rho \frac{D\vec{v}}{Dt} = -\nabla P + \frac{1}{4\pi} (\nabla \times \vec{B}) \times \vec{B}$$

$$\Leftrightarrow \rho \frac{D\vec{v}}{Dt} = -\nabla P + \frac{1}{4\pi} \left[ -\frac{1}{2} \nabla B^2 + (\vec{B} \cdot \nabla) \vec{B} \right]$$

$$\Leftrightarrow \rho \frac{D\vec{v}}{Dt} = -\nabla \left( P + \frac{B^2}{8\pi} \right) + \frac{1}{4\pi} (\vec{B} \cdot \nabla) \vec{B} \quad (11)$$

(MHD Euler Equation)

- The term  $B^2/8\pi$  is the magnetic pressure, while the  $1/4\pi (\vec{B} \cdot \nabla) \vec{B}$  term is the magnetic tension ( $\rightarrow$  see later).
- Now we know how  $\vec{B}$  affects the motion of the gas, but how do the gas motions affect/generate  $\vec{B}$ ?
- We start from the non-relativistic Ohm's Law:

$$\vec{j} = \sigma \left( \vec{E} + \frac{1}{c} \vec{v} \times \vec{B} \right) \quad (12)$$

$\sigma$  is the conductivity

- Substituting Eq. (12) into Eq. (7) gives

$$\vec{E} = \frac{c}{4\pi\sigma} \nabla \times \vec{B} - \frac{1}{c} \vec{v} \times \vec{B} \quad (13)$$

- Then this into the 3rd Maxwell eq.:

$$\partial_t \vec{B} = -c \nabla \times \vec{E} = \nabla \times (\vec{v} \times \vec{B}) - \frac{c^2}{4\pi\sigma} \nabla \times (\nabla \times \vec{B}) \quad (14)$$

- We can expand the 2nd term on the RHS:

$$\partial_t \vec{B} = \nabla \times (\vec{v} \times \vec{B}) - \frac{c^2}{4\pi\sigma} \left[ \nabla (\nabla \cdot \vec{B}) - \Delta \vec{B} \right]$$

(2nd Maxwell)

$$\Rightarrow \partial_t \vec{B} = \nabla \times (\vec{v} \times \vec{B}) + \frac{c^2}{4\pi\sigma} \Delta \vec{B} \quad (15)$$

$= \eta$  (magnetic resistivity)

(MHD induction equation)

- We see in Eq. (15) that the  $\Delta \vec{B}$  term with the magnetic resistivity  $\eta$  is a diffusion term ( $\partial_t q - \partial_x^2 q = 0$ ), which leads to diffusion of  $\vec{B}$  over time.  $\Rightarrow$  magnetic (Ohmic) diffusion.

- In the limit of infinite conductivity  $\sigma \rightarrow \infty$ , Eq. (15) simplifies to ( $\eta \rightarrow 0$ ):

$$\partial_t \vec{B} = \nabla \times (\vec{v} \times \vec{B}) \quad (16)$$

(Induction eq. in the limit of ideal MHD)

- Recall that even if the ionisation fraction is very small (say  $10^{-8}$ , e.g., in molecular clouds), the conductivity can still be very high, such that the ideal MHD approximation is good for many astrophysical gases.
- However ideal MHD breaks down for example in the dense parts of accretion discs, where non-ideal MHD is active ( $\rightarrow$  Ohm, Ambipolar, Hall diffusion).
- Note that  $\vec{J}$  and  $\vec{E}$  do not occur explicitly in the MHD equations, but are still there, and given by Eq. (12) and (13).
- Also note  $\text{div } \vec{B} = 0$  ( $\rightarrow$  immediately clear from Eq. 14).

- Finally, let's check for consistency with our very first assumption ( $S_e$  small), Eq.(1):  $S_e v \sim \frac{v^2}{c^2} J$ .

- Using the 1st Maxwell eq.:

$$S_e = \frac{1}{4\pi} \nabla \cdot \vec{E} \stackrel{(Eq.13)}{=} \frac{1}{4\pi} \nabla \cdot \underbrace{\left[ \frac{c}{4\pi\sigma} \nabla \times \vec{B} - \frac{1}{c} \vec{v} \times \vec{B} \right]}_{=0}$$

$$\Rightarrow S_e \sim \nabla \cdot \left( \frac{1}{c} \vec{v} \times \vec{B} \right)$$

$$\left. \begin{array}{l} \cdot \text{Now again } \nabla \rightarrow L^{-1} \Rightarrow S_e \sim \frac{v}{c} \frac{1}{L} B \\ \cdot \text{And from Eq.(7), } \nabla \times \vec{B} = \frac{4\pi}{c} \vec{J} \Rightarrow B \sim \frac{L}{c} J \end{array} \right\} \Rightarrow$$

$$\Rightarrow S_e \sim \frac{v}{c} \frac{1}{c} J$$

or  $\boxed{S_e v \sim \frac{v^2}{c^2} J}$ , which is Eq.(1).

Finally, the complete set of MHD equations:

mass:  $\partial_t S + \nabla \cdot (S \vec{v}) = 0$

velocity:  $\partial_t \vec{v} + (\vec{v} \cdot \nabla) \vec{v} = -\frac{1}{S} \nabla (P + B^2/8\pi) + \frac{1}{4\pi S} (\vec{B} \cdot \nabla) \vec{B}$

energy:  $\partial_t (S e_{tot}) + \nabla \cdot \left[ (S e_{tot} + P_{tot}) \vec{v} - \frac{1}{4\pi} (\vec{B} \cdot \vec{v}) \vec{B} \right] = 0$

induction:  $\partial_t \vec{B} = \nabla \times (\vec{v} \times \vec{B}) + \frac{c^2}{4\pi\sigma} \Delta \vec{B}$  ; div-free:  $\nabla \cdot \vec{B} = 0$

with  $S e_{tot} = \frac{1}{2} S v^2 + S e_{int} + B^2/8\pi$  and  $P_{tot} = P + B^2/8\pi$